

## The Eight-Puzzle



Initial state


Goal state

- State representation: (3 2845671 _ )
- Operators: Up, Down, Left, Right
- Example: (32845671_) $\underset{\text { Down }}{\Rightarrow}(32845$ _716)
- M\&C problem has < 30 possible states
- 8-puzzle has 9! possible states $=362,880$
- 15-puzzle has 16 ! possible states $=20,922,789,888,000$
- Demo



## Heuristic Function 1

## Number of misplaced tiles

 (not including the blank)

Only tile 8 is misplaced, so heuristic estimate $=1$
In other words, the heuristic is telling us that it thinks a
 solution might be reached in 1 more move.


## Heuristic Function 2



Only tiles 3, 8 and 1 are misplaced (by 2, 3, and 3 spaces, respectively) so the heuristic function evaluates to 8

In other words, the heuristic is telling us that it thinks


3 spaces

Total $=8$ a solution is reachable in 8 more moves.

Notation: $h(\mathrm{n}) \quad h($ current state $)=8$


Manhattan-distance heuristic


Manhattan-distance heuristic


Manhattan-distance heuristic










Always choosing the next state based on the lowest heuristic value is called hill climbing.


In this example, hill climbing does not work!

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 8 |
| 6 | 7 |  |

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All the nodes on the leaves are taking a step backwards (a "local minimum")

Note that this puzzle is solvable in just 12 more steps.


## The A* Algorithm

- Just like before, but we also keep track of the distance from the initial state to each intermediate state
- Choose the next node based on the sum of two values:
- How far we think we have left to go (the heuristic estimate)
- How long it took to get here
$-f(\mathrm{n})=h(\mathrm{n})+g(\mathrm{n})$
- If our heuristic function never overestimates, this algorithm is guaranteed to find the shortest path to the goal!
- Underestimating is fine, but the closer the estimate is to the true value, the faster the search will find the goal.
- If it does occasionally overestimate the number of steps left, the search process may get lost in blind alleys, or may find a suboptimal path to the goal


