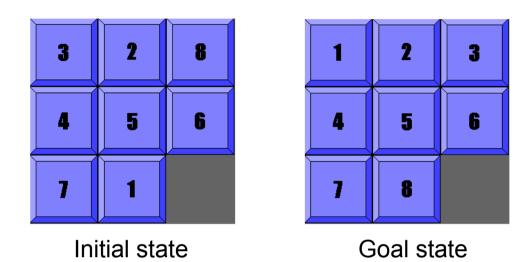
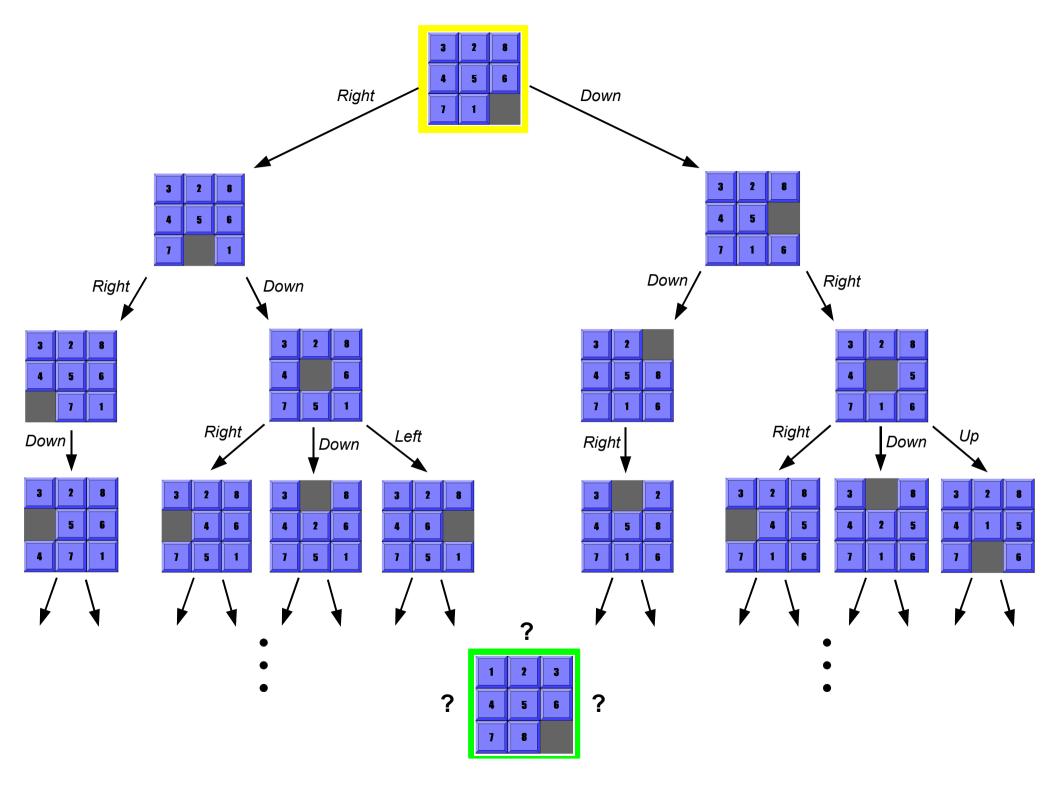


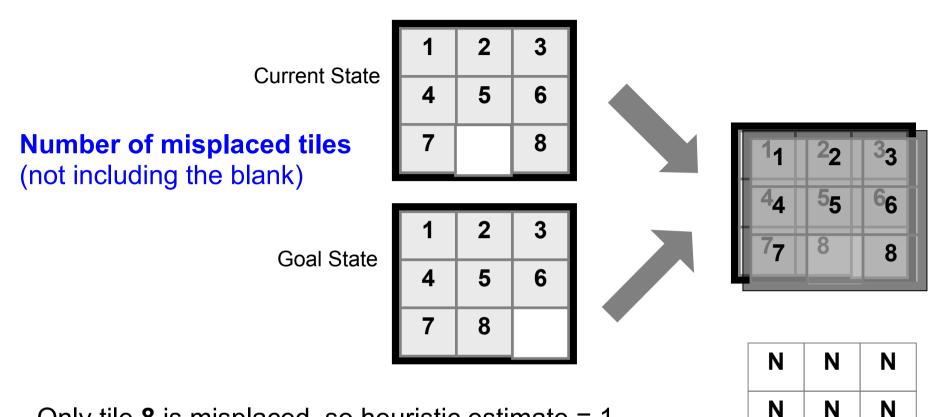
# The Eight-Puzzle



- State representation: (3 2 8 4 5 6 7 1 \_)
- Operators: Up, Down, Left, Right
- Example:  $(32845671_) \Rightarrow (32845_716)$
- M&C problem has < 30 possible states
- 8-puzzle has 9! possible states = 362,880
- 15-puzzle has 16! possible states = 20,922,789,888,000
- Demo



# **Heuristic Function 1**



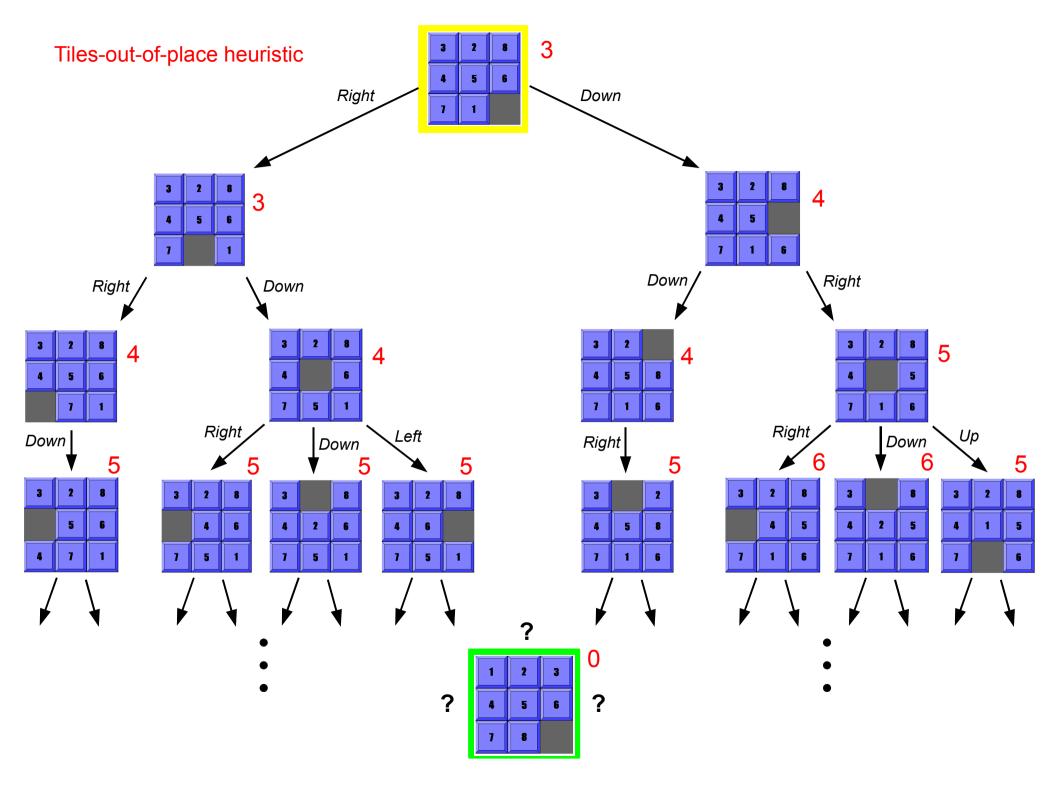
Υ

Ν

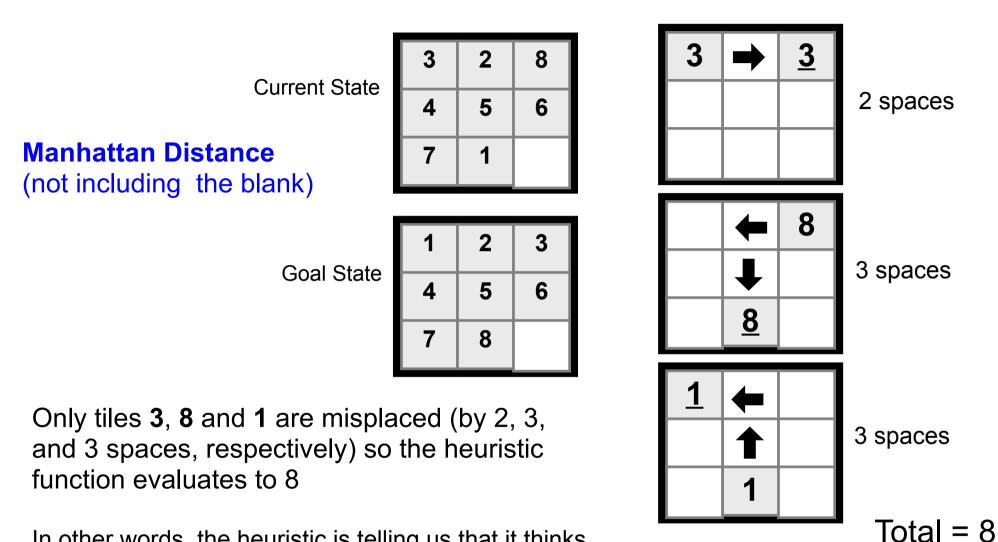
Only tile 8 is misplaced, so heuristic estimate = 1

In other words, the heuristic is telling us that it thinks a solution might be reached in 1 more move.

Notation: h(n) h(current state) = 1

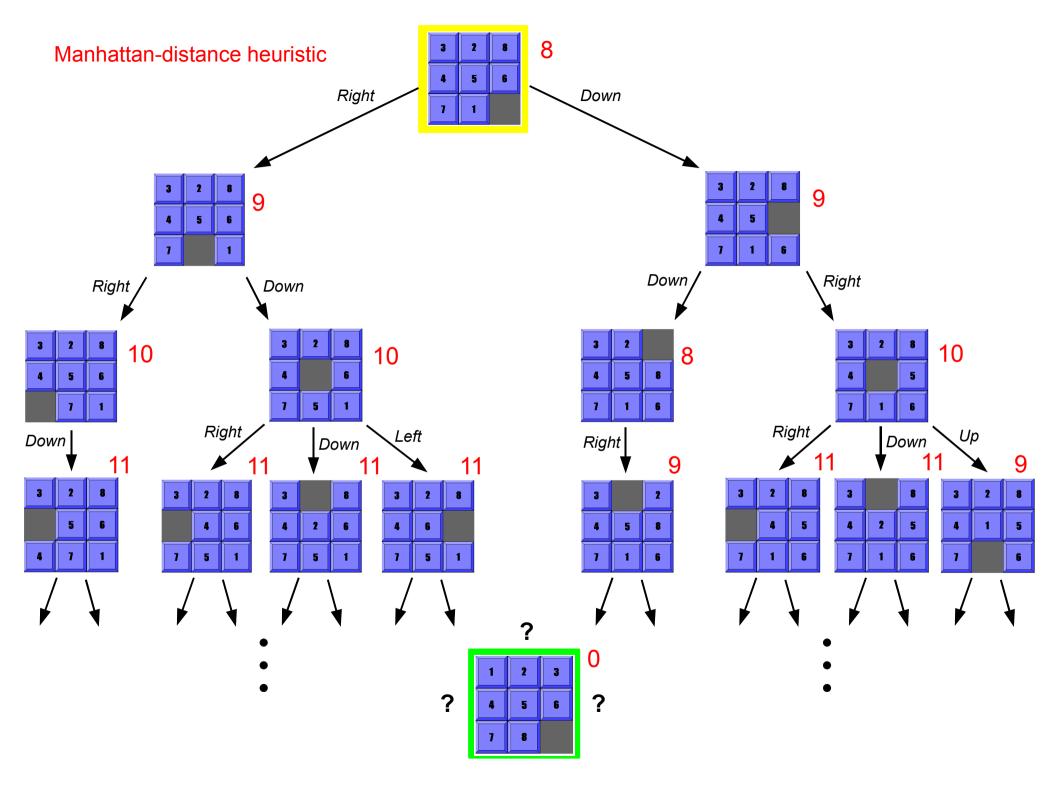


### Heuristic Function 2

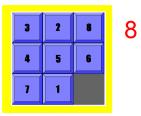


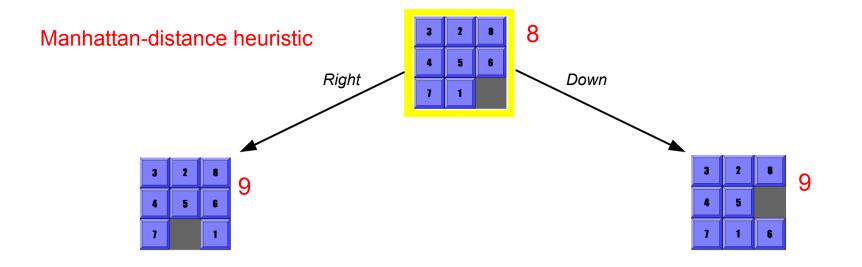
In other words, the heuristic is telling us that it thinks a solution is reachable in 8 more moves.

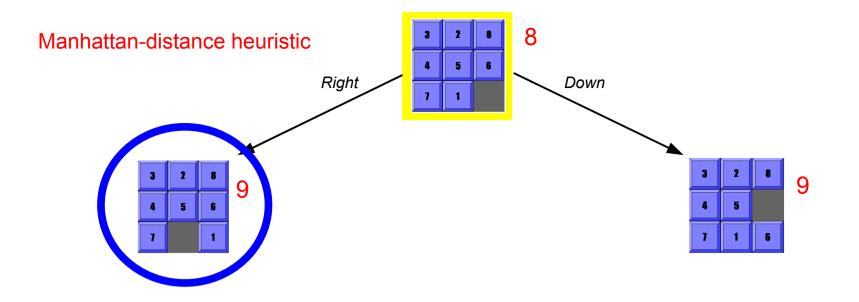
Notation: h(n) h(current state) = 8

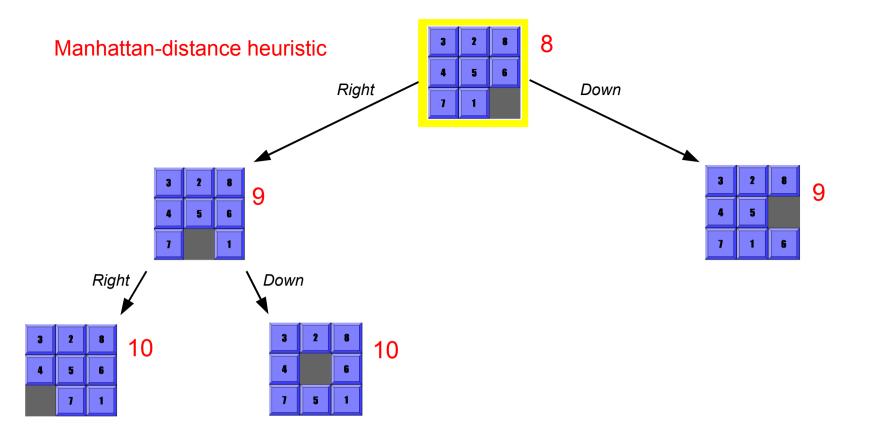


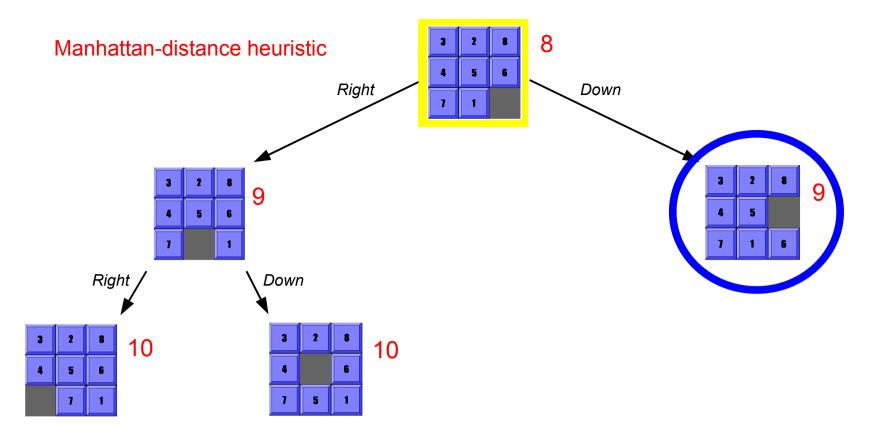
#### Manhattan-distance heuristic

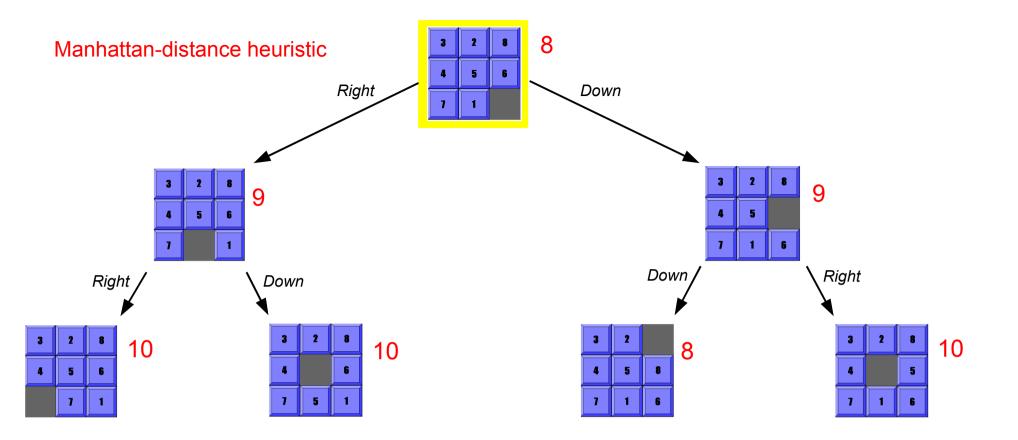


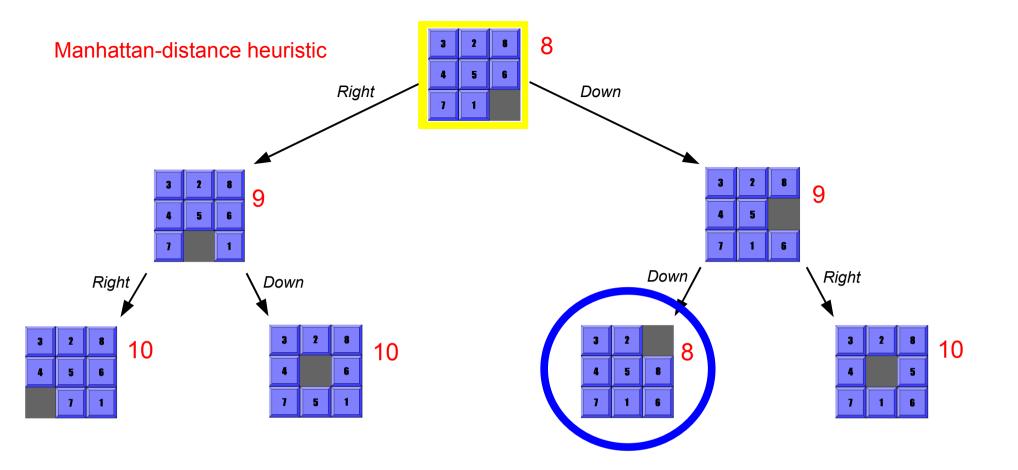


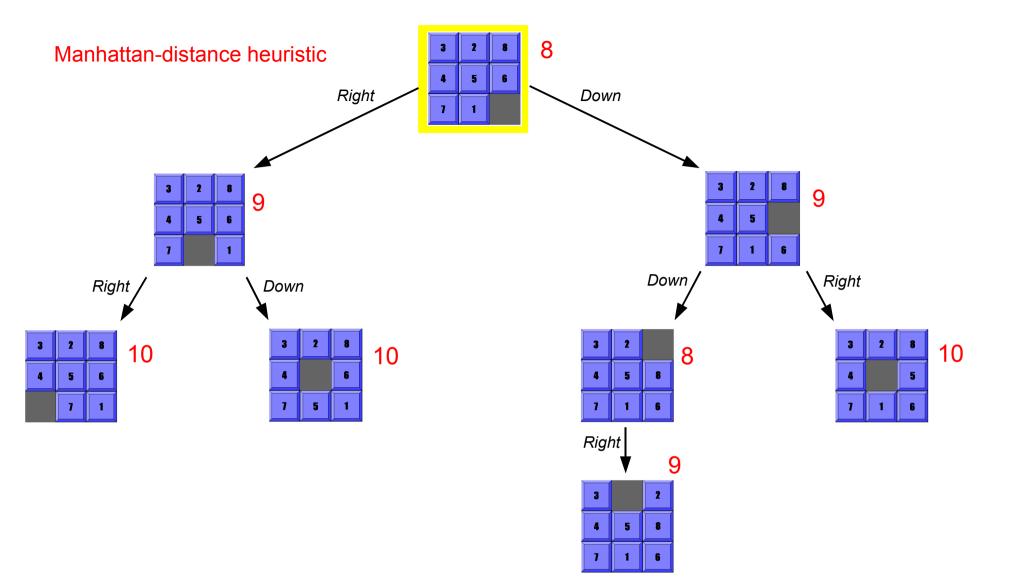


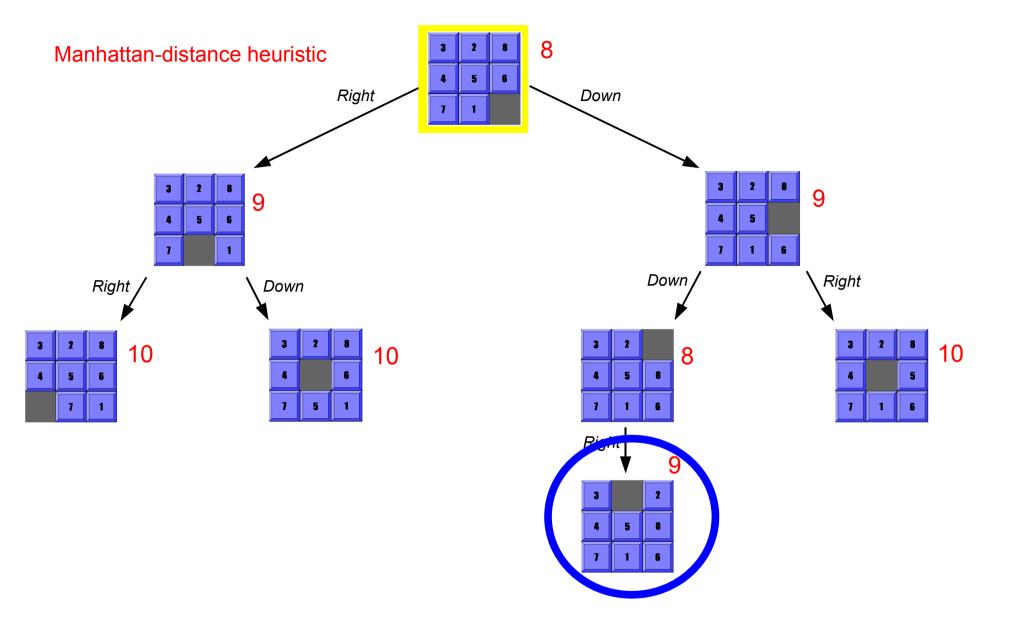


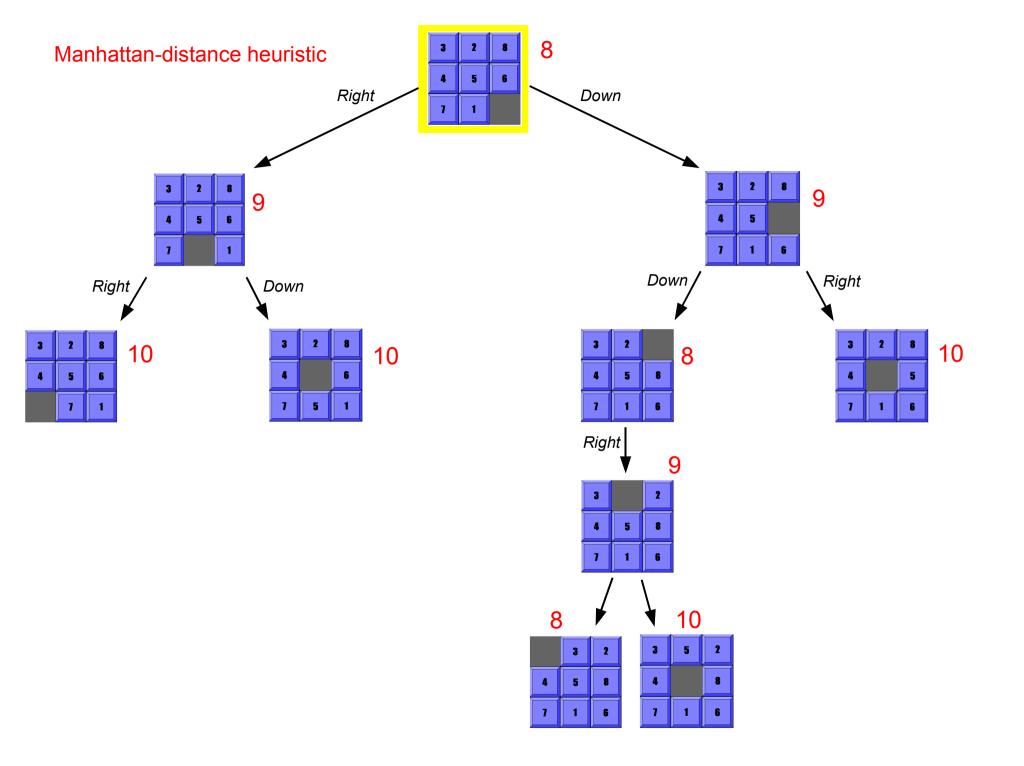


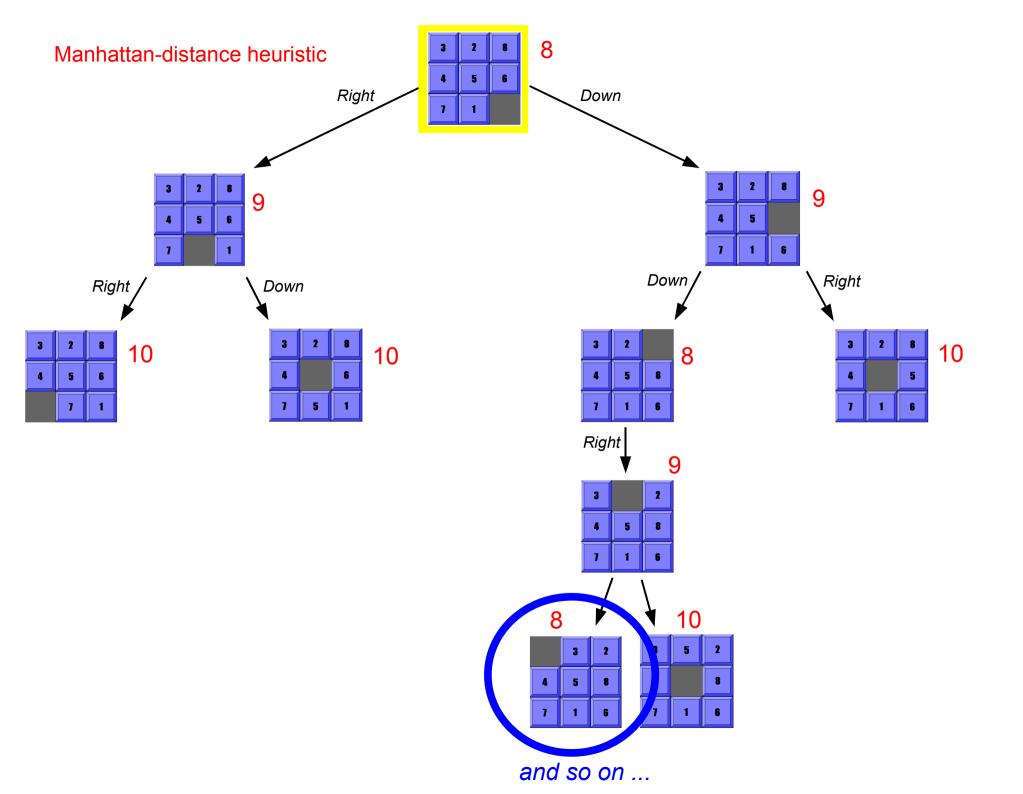








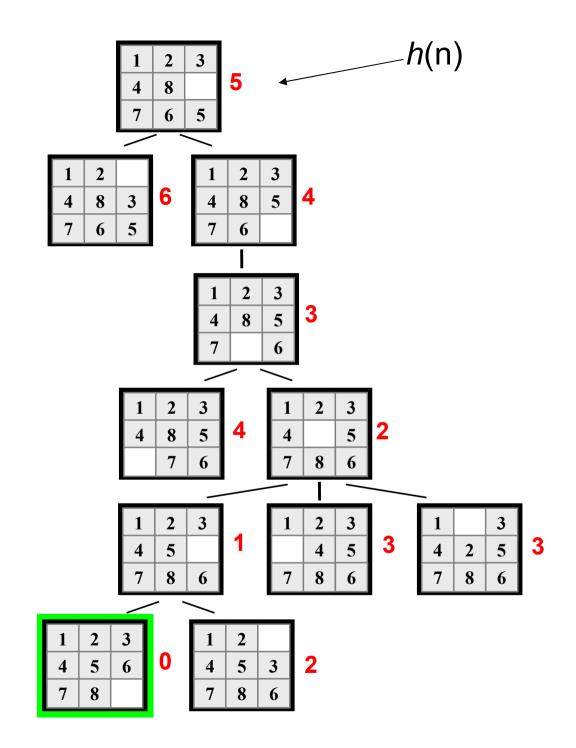




Always choosing the next state based on the lowest heuristic value is called **hill climbing**.

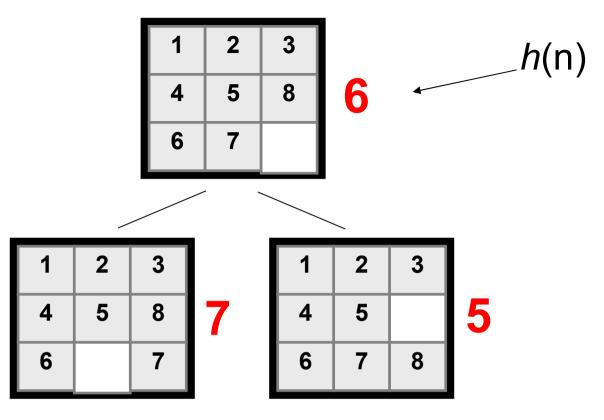
In this example, the Manhattan Distance heuristic guides us quickly to a solution.

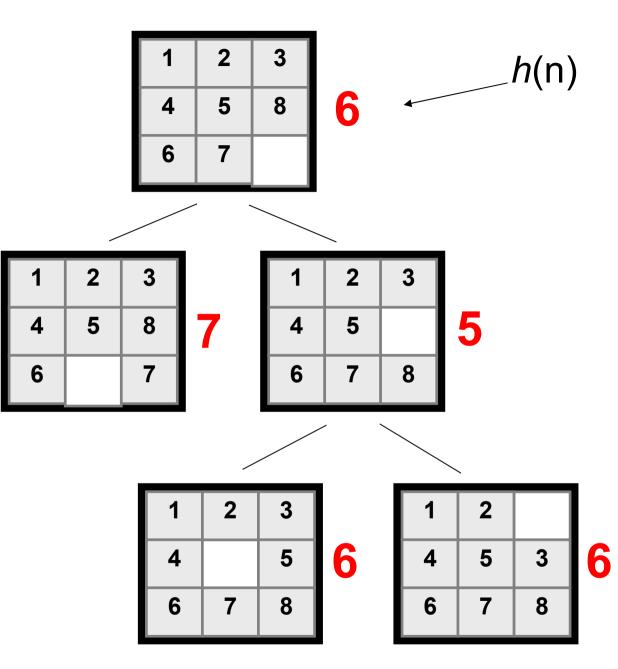
But hill climbing has a problem...



1	2	3
4	5	8
6	7	

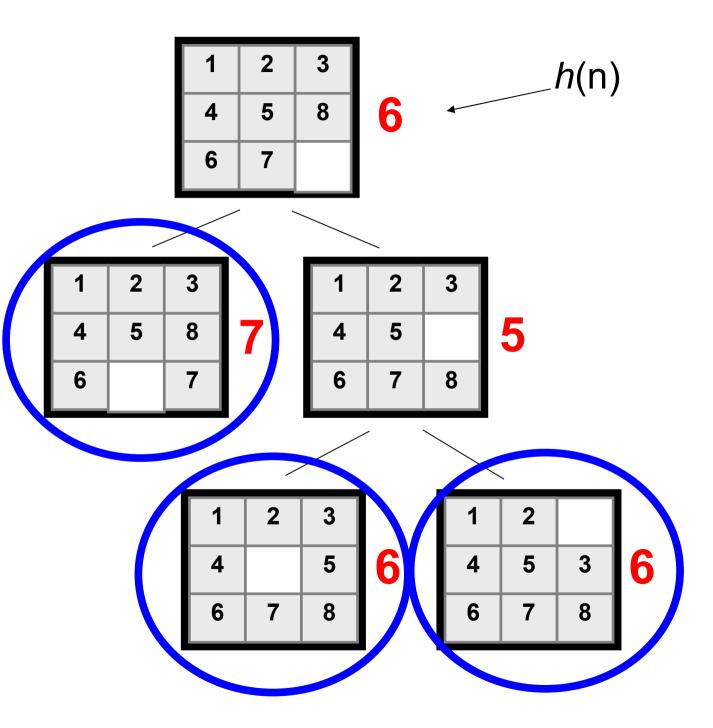
*h*(n) 6





All the nodes on the leaves are taking a step backwards (a "local minimum")

Note that this puzzle *is* solvable in just 12 more steps.



# The A\* Algorithm

- Just like before, but we also keep track of the distance from the initial state to each intermediate state
- Choose the next node based on the **sum** of two values:
  - How far we think we have left to go (the heuristic estimate)
  - How long it took to get here
  - f(n) = h(n) + g(n)
- If our heuristic function **never overestimates**, this algorithm is guaranteed to find the shortest path to the goal!
- Underestimating is fine, but the closer the estimate is to the true value, the faster the search will find the goal.
- If it *does* occasionally overestimate the number of steps left, the search process may get lost in blind alleys, or may find a suboptimal path to the goal

